

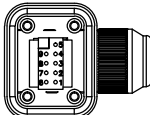
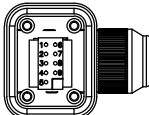
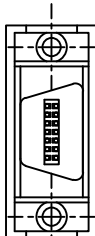
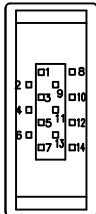
Standard:APCS-ENxxES High Flex:APCS-EFxxES	Standard:APCS-ENxxES-R High Flex:APCS-EFxxES-R
Front Direction	Rear Direction

Robot	Normal
Code	L
G01	3m
G02	5m
G03	10m
G04	20m

(Front Direction)

Robot	Normal
Code	L
G51	3m
G52	5m
G53	10m
G54	20m

(Rear Direction)

Motor Side Connector	Driver Side Connector																																																								
<div></div> <div>(Front Direction) (Rear Direction)</div> <div>Tyco Connector <u>SECTION A-A'</u></div> <table><tr><th>PIN No.</th><th>Encoder Signal</th></tr><tr><td>1</td><td>MA</td></tr><tr><td>2</td><td>SLO</td></tr><tr><td>3</td><td>—</td></tr><tr><td>4</td><td>0V</td></tr><tr><td>5</td><td>Shield</td></tr><tr><td>6</td><td>/MA</td></tr><tr><td>7</td><td>/SLO</td></tr><tr><td>8</td><td>—</td></tr><tr><td>9</td><td>+5V</td></tr></table>	PIN No.	Encoder Signal	1	MA	2	SLO	3	—	4	0V	5	Shield	6	/MA	7	/SLO	8	—	9	+5V	<div></div> <div>SOLDERING :C-C'</div> <div><u>SECTION B-B'</u></div> <table><tr><th>PIN No.</th><th>Encoder Signal</th><th>PIN No.</th><th>Encoder Signal</th></tr><tr><td>1</td><td>—</td><td>8</td><td>—</td></tr><tr><td>2</td><td>—</td><td>9</td><td>—</td></tr><tr><td>3</td><td>MA</td><td>10</td><td>—</td></tr><tr><td>4</td><td>/MA</td><td>11</td><td>—</td></tr><tr><td>5</td><td>SLO</td><td>12</td><td>—</td></tr><tr><td>6</td><td>/SLO</td><td>13</td><td>—</td></tr><tr><td>7</td><td>0V</td><td>14</td><td>+5V</td></tr><tr><td>Plate</td><td></td><td>SHIELD</td><td></td></tr></table>	PIN No.	Encoder Signal	PIN No.	Encoder Signal	1	—	8	—	2	—	9	—	3	MA	10	—	4	/MA	11	—	5	SLO	12	—	6	/SLO	13	—	7	0V	14	+5V	Plate		SHIELD	
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Plate		SHIELD																																																							

UNIT	MATE	PROJ	SCALE
mm	R/L		
PART NAME	OPS08GC003	DWG. NO	T65A
DESIGNED BY	CHECKED BY	APPROVED BY	
J.C.Y	J.H.R	Traci Lee	
140709	140716	140716	
PARKER KOREA LTD.			