# www.comoso.com **r Grippers -ICL** eries

- 180° angular gripper: The full jaw opening (180°) means that the part can be direct fed, avoiding any release movement by the robot or by the actuator.
- Multiple mounting locations: DIRECTCONNECT<sup>™</sup> mounting on back of body (sizes 12-25). Standard mounting on top.
- Compact gripper: This gripper is designed for use in confined spaces.
- Multipurpose gripper: Several accessories (adjustable stop, magneto resistive or inductive sensors\*) allow this gripper to be used in a number of applications.
- **Harsh environments:** Shielded design repels chips and other particulate from internal drive mechanism. \* Inductive sensors not available on CT-12

### **Technical Specifications:**

| Pneumatic Specifications<br>Pressure Operating Range<br>Cylinder Type<br>Dynamic, Seals | <b>Imperial</b><br>40-100 psi<br>Double A<br>Internally Lubrica | <b>Metric</b><br>3-7 bar<br>cting<br>ated Buna-N |  |
|---|---|--|--|
| Dynamic Seals   | Internally Lubrica  | ernally Lubricated Buna-N                        |  |
| valve Required to Operate   | 4-way, 2-p  | osition  |  |

### **Air Quality Requirements**

ŀ 1

| Air Filtration  | 40 Micron or Better        |
|-----------------|----------------------------|
| Air Lubrication | Not Necessary*             |
| Air Humidity    | Low Moisture Content (dry) |
|                 | ,                          |

**Temperature Operating Range** -30°~180° F Buna-N Seals (Standard) -35°~80° C Viton<sup>®</sup> Seals (Optional) -20°~300° F -30°~150° C

### **Maintenance Specifications**

| Expected Life   |                     |
|---|---------------------|
| Normal Application  | 5 million cycles    |
| w/ Preventative Maintenance                                 | 10+ million cycles* |
| Field Repairable  | Yes                 |
| Seal Repair Kits Available                                  | Yes                 |
| *Addition of lubrication will greatly increase service life | 9                   |

**Mounting Information:** 

### Grippers can be mounted & operated in any orientation

Gripper is located from the top with 2 dowel pins and assembled with 2 screws.

DIRECTCONNECT mounting pattern: Gripper is located with 2 dowel pins and assembled with 4 screws. Alternative pattern: Gripper is located with 2 dowel pins and assembled with 2 screws.



Fingers are centered over the jaws, located with 1 dowel pin and assembled with 2 screws.

Gripper can be operated utilizing top manifold air ports.

2.32

The gripper

is protected from falling

debris when it is mounted and operated upside down.



DIRECTCONNECT

DCT/CT SERIES

2.33

1.5° before reaching the fully gripped position. Jaws have to be designed

for a 0° gripping position (parallel jaws)

# ANGULAR GRIPPER DCT-12M **180° SERIES**

Maximum Moment My

Maximum Moment Mx

\*Capacities are per set of jaws and are not simultaneous

10 in.-Ibs.

10 in.-lbs.

1.1 Nm

1.1 Nm

3 in.-lbs.

3 in.-lbs.

0.3 Nm

0.3 Nm





Please see back cover for DE-STA-CO Global Locations. www.destaco.com

ADJUSTABLE

STOP KIT (BR



### ANGULAR GRIPPER DCT-16M 180° SERIES



SERIES

50

# ANGULAR GRIPPER DCT-20M **180° SERIES**





1.02 [26

0.24 [6]

Maximum Moment Mz

\*Capacities are per set of jaws and are not simultaneous

53 in.- lbs.

6 Nm

13 in.-Ibs.

1.5 Nm

DCT SERIES



Maximum Moment Mz

\*Capacities are per set of jaws and are not simultaneous

89 in.-Ibs.

10 Nm

22 in.-Ibs.

2.5 Nm

### ANGULAR GRIPPER DCT-25M 180° SERIES



DIRECTCONNEC

SERIES

50

# ANGULAR GRIPPER CT-32M 180° SERIES

SERIES

5







# **ANGULAR GRIPPER CT-40M 180° SERIES**



SERIES

5

# ANGULAR GRIPPER CT-50M 180° SERIES

Maximum Moment Mz

\*Capacities are per set of jaws and are not simultaneous

266 in.- lbs.

30 Nm

66 in.-Ibs.

7.5 Nm





2.38 [60.0, 0.87 [22] 0.7

Sensors Ø 0.47 [12

0.30

0.83 [2





# **DCT/CT Series Exploded View**

| ltem | Qty | Name           |  |
|------|-----|----------------|--|
|      |     |                |  |
| 01   | 1   | Body           |  |
| 02   | 1   | Driver         |  |
| 03   | 1   | Piston         |  |
| 04   | 2   | Jaw            |  |
| 05   | 1   | Washer         |  |
| 06   | 1   | Сар            |  |
| 07   | 1   | Shielded Plate |  |
| 08   | 2   | Wiper Cover    |  |
| 09   | 2   | Drive Pin      |  |
| 10   | 2   | Pivot Pin      |  |
| 54   | 1   | Magnet         |  |

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

#### **Assembly Procedure**

- 1) Lubricate and install the seals into cap (x1), piston (x2) and body (x1)
- 2) If top air ports are used, clear them and plug the side air ports on the body (#1)
- 3) Lubricate the sloping rack of jaws (#4)
- 4) Install both drive pins (#9) into driver (#2) through sloping racks of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 5) Lock drive pins in the driver with screws, tightening down on to the flat surface of the pins.
- 6) Position driver and jaws assembly into body.
- 7) Install both pivot pins (#10) into body, through the bore of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 8) Pivot pin locking:
  - DCT-12 (not shown): lock pivot pins into body with screws, tightening down on to the flat surface of the pins (pins are fixed into body and rotating into jaws)
  - DCT-16 to CT-50: lock pivot pins into jaws with screws, tightening down on to the flat surface of the pins (pins are fixed into jaws and rotating into body)
- 9) Magnet mounting:
  - DCT-12 to DCT-20: install the magnet (#54) on the washer (#5)
  - DCT-25 to CT-50 (not shown): install magnet (#54) onto piston (#3) and lock it by means of its retaining ring.
- 10) Piston mounting:
  - DCT-12 to DCT-20: insert the piston and the washer with magnet into body. Fix the assembly at the end of the driver with screw.
  - DCT-25 to CT-50 (not shown): insert the piston with magnet into body. Fix the assembly at the end of the drivers with screw.
- 11) Check unit operation unladen.
- 12) Install the cap (#6) into body and lock it by means of its retaining ring.
- 13) Place both wiper covers (#8) into body and lock them with their screws.
- 14) Fix the shielded plate (#7) onto body with both screws.

#### SK Seal Repair Kit Order #'s See Product Data Sheets



密站

### **DCT/CT Series Assembled View**





### Item Qty Name

| 01 | 1 | Body           |
|----|---|----------------|
| 02 | 1 | Driver         |
| 03 | 1 | Piston         |
| 04 | 2 | Jaw            |
| 05 | 1 | Washer         |
| 06 | 1 | Сар            |
| 07 | 1 | Shielded Plate |
| 08 | 2 | Wiper Cover    |
| 09 | 2 | Drive Pin      |
| 10 | 2 | Pivot Pin      |
| 54 | 1 | Magnet         |

**NOTE:** Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

### **Accessory Installation & Adjustment Instructions**



#### **Installation - Adjustment Stop**

- 1) Unscrew both screws for mounting of the shielded plate and remove it.
- 2) Fix the new shielded plate (#1) and the stop (#2) onto body with both screws (#3)
- 3) Install the locknut system (#4) and (#5) on the stop.
- 4) Tighten screw for maximum target jaw opening and lock with locknut.



### **Installation - Inductive Sensor Holders**

- 1) Fix the flags (#1) at the end of pivot pins with their screws (#2)
- 2) Holder mounting:
  - DCT-16M to DCT-32M: fix holder (#3) and spacer (#5) onto body with both screws (#6)
    DCT-40M to DCT-50M: fix holder (#3) onto body with both screws (#6)
- 3) Sensor mounting:
  - DCT-16M to DCT-20M: unscrew lightly both screws for mounting (#6) of holder and insert sensor (#8, not included) into it. Position sensor so that it senses up on flag. Lock the sensor by tightening both screws.
  - DCT-25M to DCT-32M: unscrew lightly screw (#7) on holder and insert sensor (#8, not included) into it. Position sensor so that it senses up the flag. Lock the sensor by tightening screw.
  - CT-40M to CT-50M: insert sensor (#8, not included) in stop into holder. Lock the sensor by tightening the collar holder with both screws (not shown).

4) Adjust flag position by unscrewing their screws for desired sensing positions.

