Angular Grippe

• 180° angular gripper:

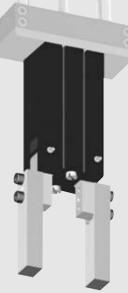
The full jaw opening (180°) means that the part can be direct fed, avoiding any release movement by the robot or by the actuator.

- Multiple mounting locations: DIRECTCONNECT™ mounting on back of body (sizes 12-25). Standard mounting on top.
- Fail safe operation: The force supplied from the internal spring can be used to maintain gripping force if the gripper looses air pressure.
- Compact gripper: This gripper is designed for use in confined spaces.

Multipurpose gripper:

Several accessories (adjustable stop, magneto resistive or inductive sensors) allow this gripper to be used in a number of applications.

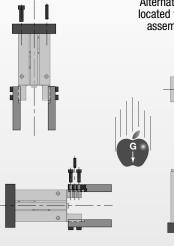
Harsh environments: Shielded design repels chips and other particulate from internal drive mechanism.



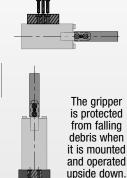
Mounting Information:

Grippers can be mounted & operated in any orientation

Gripper is located from the top with 2 dowel pins and assembled with 2 screws.



Fingers are centered over the jaws, located with 1 dowel pin and assembled with 2 screws. **DIRECTCONNECT** mounting pattern: Gripper is located with 2 dowel pins and assembled with 4 screws. Alternative pattern: Gripper is located with 2 dowel pins and assembled with 2 screws.



Gripper can be operated utilizing top manifold air ports.

Technical Specifications:

Pneumatic Specifications Pressure Operating Range

Cylinder Type

Dynamic Seals

Valve Required to Operate

Air Quality Requirements

Air Filtration Air Lubrication Air Humidity

Assist or Single Acting Spring Return **Internally Lubricated Buna-N** 4-way, 2-position

Double Acting Spring

Metric

4-7 bar

Imperial

60-100 psi

40 Micron or Better Not Necessary* **Low Moisture Content (dry)**

Temperature Operating Range

-30°~180° F Buna-N Seals (Standard) -35°~80° C Viton® Seals (Optional) -20°~300° F -30°~150° C

Maintenance Specifications[†]

Expected Life Normal Application w/ Preventative Maintenance Field Repairable

5 million cycles 10+ million cycles* Yes Yes

Seal Repair Kits Available

*Addition of lubrication will greatly increase service life †See Maintenance Section





2.45







Size -12M

Style: Stroke: **Grip Force:** Weight:

90° each finger 9 lbs 0.26 lbs 0.12 Kg

See **2.46**

40 N

Style -DCT-RE Angular Gripper

Size -16M

Stroke: Grip Force: Weight:

DCT-16M-RE 90° each finger 19 lbs 87 N 0.44 lbs 0.20 Kg

See **2.47**

Style -DCT-RE Angular Gripper

Size -20M

Style: Stroke: Grip Force: Weight:

DCT-20M-RE 90° each finger 32 lbs 141 N 0.73 lbs 0.33 Kg

See 2.48 Page

Style -DCT-RE Angular Gripper

Size -25M



Stroke: Grip Force: Weight:

90° each finger 45 lbs 199 Nm 1.26 lbs 0.57 Kg

See **2.49**

Style -CT-RE Angular Gripper

Size -32M

Stroke: Grip Force: Weight:

CT-32M-RE 90° each finger 79 lbs 353 N 1.83 lbs 0.83 Kg

See **2.50**

Style-CT-RE Angular Gripper

Size -40M

Stroke: Grip Force: Weight:

CT-40M-RE 90° each finger 133 lbs 592 N 1.39 Kg 3 06 lbs

See **2.51**

Style-CT-RE Angular Gripper

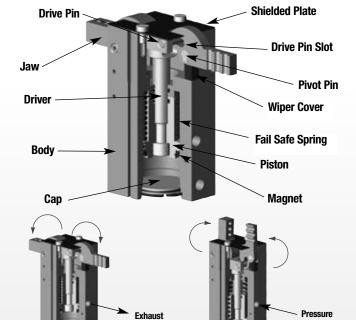
Size -50M



Style: Grip Force: Weight:

CT-50M-RE 90° each finger 201 in-lbs 893 N 4.87 lbs 2.21 Kg

See **2.52**



Operating Principle

Product Features

Adjustable Stop

Accessory (BR) in order to

adjust the opening of jaws, between 0° to 180°

Shielded

Plate and Wiper

Covers

Gripper body is shielded

to repel chips and other

particulate from internal

drive mechanism

DIRECTCONNECT

Mounting Patterns

DIRECTCONNECT™

mounting surface on back

of body (sizes 12-25)

Fail Safe Spring

Internal spring allows

part with loss of air

pressure

Multiple **Air Ports**

Side or top air

ports (top ports require 0-ring)

Gripper Attachment

Gripper mounting from

side or bottom

Viton Seals Viton seals for high temperatures (-20°F to +300°F / -30° \sim 150° C)

are optional

Quality

Components

Made from aluminum

alloy anodized with Teflon™ impregnation.

The gripper's main

components are made

of heat treated steel.

Inductive Sensor Mounting Kit

Accessory (SD) in order

to control jaw position: comes with 2 holders for

tubular sensors and

2 adjustable flags (except size -12)

Magneto Resistive

Sensor Mounting Kit

The gripper comes with adjustable slots for the 2 magnetic sensors (to control jaw position)

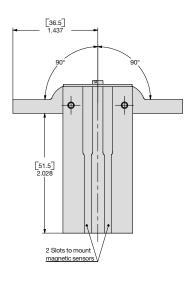
> A double acting piston, with a ring magnet for magneto resistive sensing, is connected to a fork driver on which 2 drive pins are fixed.

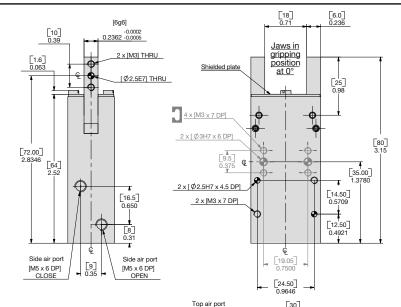
Pressure

- Jaw rotation is synchronized with the drive pin-jaw assembly.
- . Sliding in these slots, drive pins convert vertical motion of the piston into rotating opposite synchronous motion of both jaws.
- Each jaw has a useful rotation stroke of 90°, between the 90° open position and the 0° gripping position, plus a gripping over-stroke of approximately 1.5° before reaching the fully gripped position. Jaws have to be designed for a 0° gripping position (parallel jaws)
- The fail safe spring allow the gripper to retain the component should the air supply fail or for the gripper to be used in single acting mode.

Exhaust







Specifications

Total Rated Grip Force, **F** @ 100 psi [7 bar] **L** = 1 in. [25mm] @ 0°.....

Pressure Range.. Cylinder Bore Ø Displacement Temperature Range Standard Seals..... Viton® Seals

Actuation (open/close) Accuracy..... ±0.0028 in. Repeatability..... Valve required to actuate single acting Valve required to actuate double acting....

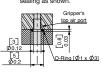
DCT-12M-RE

9 lbs. 90° of stroke for each finger 0.26 lbs. 0.12 Kg 60-100 psi 4-7 Bar 0.472 in. 12 mm 0.117 in³. 1.92 cm³

-35°~80° C -30°~180° F -30°~150° C -20°~300° F 0.08 / 0.05 sec. ±0.07 mm

±0.05 mm

3-way, 2-position 4-way, 2-position Our grippers are supplied with open side air ports and top air ports plugged. When operating top air ports, produce manifold sealing as shown



[30] 1.18 [M3 x 5.5 DP] OPEN (supplied plugged [24.50] 0.9646 2 x [M3 x 7 DP] 2 x [Ø 2.5H9 x 4.5 DP] [14.50] 0.5709 [20] 0.79 Top air port ¢ [8.6] •0.339

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Ç Dimensions are symmetrical about centerline Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ $0.0000 = \pm .0005$ Metric Threads Course Pitch

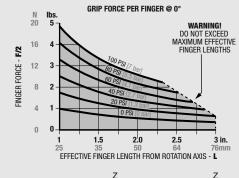
F/2

1.1 Nm

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ NOTE: Jaws have to be designed for a 0° gripping position (parallel jaws). Jaws will close 1.5° past parallel. To limit shocks at the end of an opening or closing stroke, it is highly recommended to design jaws with minimal inertia (as light and short as possible). Flow Controls make it possible to reduce the rotation speed and are highly recommended.

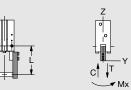
Loading Information

How to Order: (Order Accessories separately from Basic Model)

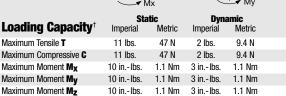




MRECTCONN



†Capacities are per set of jaws and are not simultaneous



1.1 Nm

3 in.-lbs.

10 in.-lbs.

BASIC MODEL VITON® SEALS DCT - 12M - RE -**NOTE:** DCT-12-RE can be used as an exact replacement for CT-12-RE SIZE SPRING

(supplied plugged)

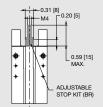
SENSOR ACCESSORIES

OHSP-017 PNP Magneto Resistive Sensor Short Barrel w/Qk Disc* 1 or 2 NPN Magneto Resistive Sensor Short Barrel w/Qk Disc* **OHSN-017** 1 or 2 Quick Disconnect 2 Meter Cable Length CABL-010 1 or 2 Quick Disconnect 5 Meter Cable Length* CABL-013 1 or 2

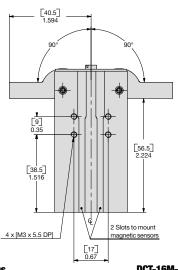
PNEUMATIC ACCESSORIES

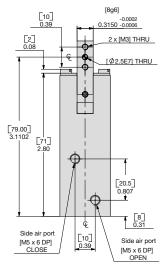
*Sensor and cable sold separately.

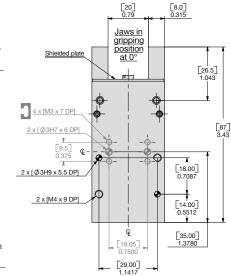
Adj. Flow Control M5 Elbow - 6mm OD Push-in (Metric) VLVF-008 1 or 2 Buna-N Seal Repair Kit **SLKT-159** Viton® Seal Repair Kit SLKT-159V 1 **MOUNTING ACCESSORIES** Adjustment Stop Kit (1 Shielded Plate + 1 Stop) KP-DCT12-BR











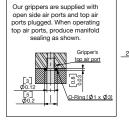
ANGULAR GRIPPER DCT-16M-RE

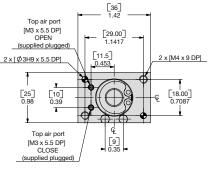
180° SERIES

Specifications

DCT-16M-RE

Total Rated Grip Force, F @ 100 psi [7 bar]		
L = 1 in. [25mm] @ 0°	19 lbs.	87 N
Stroke		
Weight	0.44 lbs.	0.20 Kg
Pressure Range	60-100 psi	4-7 Bar
Cylinder Bore Ø	0.630 in.	16 mm
Displacement	0.251 in ³ .	4.12 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation (open/close)	0.15 / 0.12 sec.	
Accuracy	±0.0028 in.	±0.07 mm
Repeatability	±0.002 in.	±0.05 mm.
Valve required to actuate single acting		
Valve required to actuate double acting	4-way, 2-position	





NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Ç Dimensions are symmetrical about centerline

Maximum Moment Mz

†Capacities are per set of jaws and are not simultaneous

26 in.-lbs.

2.9 Nm

6 in.-lbs.

0.7 Nm

0 Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm]

0 Metric Threads Course Pitch

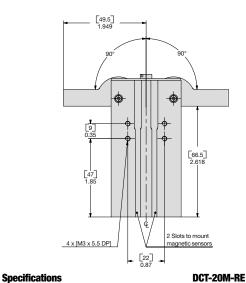
Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ 0.0000 = +.0005

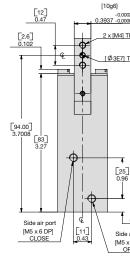
Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ NOTE: Jaws have to be designed for a 0° gripping position (parallel jaws). Jaws will close 1.5° past parallel. To limit shocks at the end of an opening or closing stroke, it is highly recommended to design jaws with minimal inertia (as light and short as possible). Flow Controls make it possible to reduce the rotation speed and are highly recommended.

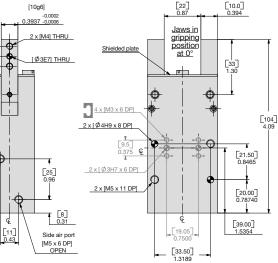
How to Order: (Order Accessories separately from Basic Model) **Loading Information BASIC MODEL VITON® SEALS GRIP FORCE PER FINGER @ 0°** DCT - 16M - RE -WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE FINGER LENGTHS NOTE: DCT-16-RE can be used as an exact replacement for CT-16-RE FINGER FORCE - F/2 30 SENSOR ACCESSORIES* **OHSP-017** PNP Magneto Resistive Sensor Short Barrel w/Qk Disc* 1 or 2 20 NPN Magneto Resistive Sensor Short Barrel w/Qk Disc* **OHSN-017** 1 or 2 Inductive Sensor Mounting Kit (mounts 2 sensors) SDCT16-20 1 10 4mm PNP Inductive Sensor with Quick Disconnect* **OISP-014** 1 or 2 4mm NPN Inductive Sensor with Quick Disconnect* **OISN-014** 1 or 2 0 Quick Disconnect 2 Meter Cable Length* CABL-010 1 or 2 Quick Disconnect 5 Meter Cable Length CABL-013 1 or 2 EFFECTIVE FINGER LENGTH FROM ROTATION AXIS - L **PNEUMATIC ACCESSORIES** Adj. Flow Control M5 Elbow - 6mm OD Push-in (Metric) VLVF-008 1 or 2 **SLKT-160** Buna-N Seal Repair Kit Viton® Seal Repair Kit SLKT-160V **MOUNTING ACCESSORIES** Adjustment Stop Kit (1 Shielded Plate + 1 Stop) **KP-DCT16-BR -** F/2 ct *Sensor and cable sold separately. Static **Dynamic Loading Capacity**[†] Metric Metric Imperial Imperial Maximum Tensile T 20 lbs. 90 N 4 lbs. 18 N Maximum Compressive C 20 lbs. 90 N 4 lbs. 18 N Maximum Moment Mx 26 in.-lbs. 2.9 Nm 6 in.-lbs. 0.7 Nm Maximum Moment My 26 in.-lbs. 2.9 Nm 6 in.-lbs. 0.7 Nm

MECTCONN





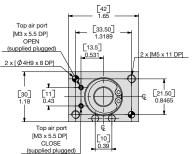




90° of stroke for each finger 0.33 Kg 4-7 Bar 20 mm 7.92 cm³ -35°~80° C -30°~150° C

Our grippers are supplied with open side air ports and top air ports plugged. When operating top air ports, produce manifold sealing as shown





Total Rated Grip Force, **F** @ 100 psi [7 bar]

L = 1.25 in. [32mm] @ 0°
Stroke
Weight
Pressure Range
Cylinder Bore Ø
Displacement
Temperature Range
Standard Seals
Viton® Seals
Actuation (open/close)
Accuracy
Repeatability
Valve required to actuate single acting
Valve required to actuate double acting

-20°~300° F

32 lbs.

0.73 lbs.

0.787 in.

0.483 in³.

-30°~180° F

60-100 psi

0.20 / 0.14 sec. ±0.08 mm ±0.003 in. ±0.002 in. ±0.05 mm 3-way, 2-position

4-way, 2-position

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about $\Rightarrow \oplus$ Third Angle Projection

†Capacities are per set of jaws and are not simultaneous

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm

GRIP FORCE PER FINGER @ 0°

0 Metric Threads Course Pitch

WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE

FINGER LENGTHS

141 N

Metric [mm] Imperial in. $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ $0.00 = \pm .01$ $0.000 = \pm .005$ 0.0000 = +.0005

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

NOTE: Jaws have to be designed for a 0° gripping position (parallel jaws). Jaws will close 1.5° past parallel. To limit shocks at the end of an opening or closing stroke, it is highly recommended to design jaws with minimal inertia (as light and short as possible).

Flow Controls make it possible to reduce the rotation speed and are highly recommended.

VITON® SEALS

Loading Information

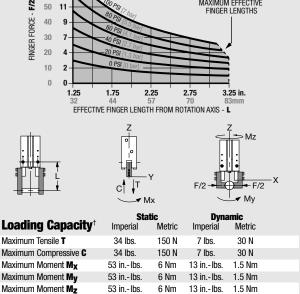
N 70 lbs. 16

60 13

50 11

How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL





2x[Ø5 H9 x10DP]

[127] 5.00

gripping position

at 0°

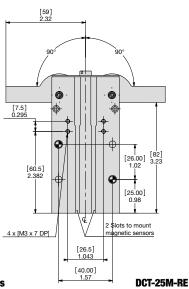
0

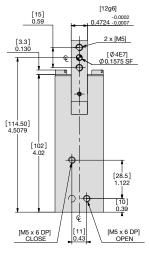
0 Q.

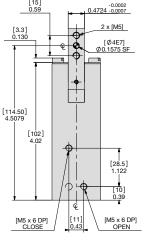
Shielded plate

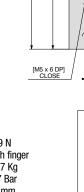
4 x [M5 x 11 DP]

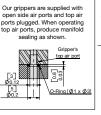
2 x [Ø5H7 x 10 DP

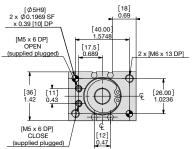












[38.10] 1.5000

Specifications Total Rated Grip Force, **F** @ 100 psi [7 bar]

L = 1.75 in. [44mm] @ 0°..... 45 lbs. 199 N Stroke..... 90° of stroke for each finger 1.26 lbs. 0.57 Kg Pressure Range..... 60-100 psi 4-7 Bar Cylinder Bore Ø 0.984 in. 25 mm Displacement 0.909 in³. 14.9 cm³ Temperature Range -35°~80° C Standard Seals -30°~180° F Viton® Seals -20°~300° F -30°~150° C Actuation (open/close)..... 0.25 / 0.19 sec. ±0.08 mm

Repeatability..... Valve required to actuate single acting Valve required to actuate double acting....

 ± 0.002 in. ±0.05 mm. 3-way, 2-position 4-way, 2-position

UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

0 Imperial in. Metric [mm] $\triangleright \Phi$ Ç $0.00 = \pm .01$ $0.000 = \pm .005$ $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ Dimensions are All Dowel Holes are SF (Slip Fit). Third Angle Projection Metric Threads Course Pitch symmetrical about Locational Tolerance ±.0005" or [±.013mm] 0.0000 = +.0005

NOTE: DIRECTCONNECT™ DIMENSIONS ARE SHOWN IN BLUE

NOTE: Jaws have to be designed for a 0° gripping position (parallel jaws). Jaws will close 1.5° past parallel. To limit shocks at the end of an opening or closing stroke, it is highly recommended to design jaws with minimal inertia (as light and short as possible).

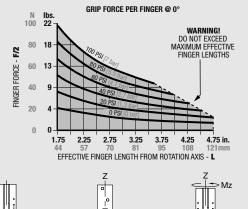
Flow Controls make it possible to reduce the rotation speed and are highly recommended.

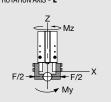
VITON® SEALS

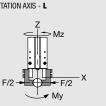


How to Order: (Order Accessories separately from Basic Model)

BASIC MODEL



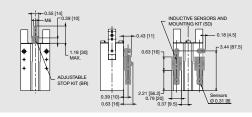




	C T Mx		F/2 F/2 X		X
Loading Capacity [†]	Sta Imperial	tic Metric	Dyna Imperial	mic Metric	
Maximum Tensile T	46 lbs.	205 N	9 lbs.	41 N	
Maximum Compressive C	46 lbs.	205 N	9 lbs.	41 N	
Maximum Moment M _X	89 inlbs.	10 Nm	22 inlbs.	2.5 Nm	
Maximum Moment My	89 inIbs.	10 Nm	22 inlbs.	2.5 Nm	
Maximum Moment Mz	89 inlbs.	10 Nm	22 inlbs.	2.5 Nm	
†Capacities are per set of jaws and are not simultaneous					

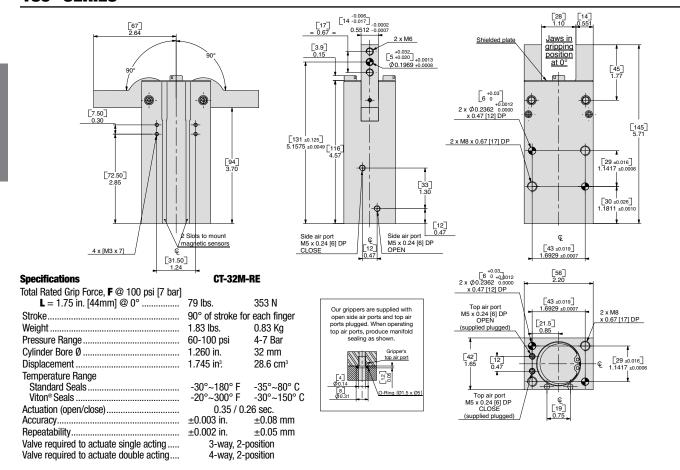


DCT - 25M - RE -



ANGULAR GRIPPER CT-32M-RE 180° SERIES





UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Ç Dimensions are symmetrical about Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm

0 Metric Threads Course Pitch

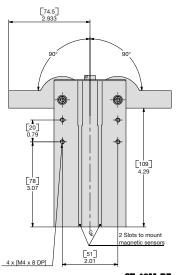
Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ 0.0000 = +.0005

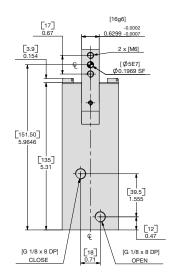
Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$

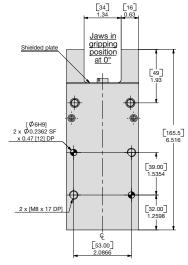
NOTE: Jaws have to be designed for a 0° gripping position (parallel jaws). Jaws will close 1.5° past parallel. To limit shocks at the end of an opening or closing stroke, it is highly recommended to design jaws with minimal inertia (as light and short as possible). Flow Controls make it possible to reduce the rotation speed and are highly recommended.

Loading Information How to Order: (Order Accessories separately from Basic Model) **BASIC MODEL VITON® SEALS** GRIP FORCE PER FINGER @ 0° N 180 CT - 32M - RE -WARNING! DO NOT EXCEED MAXIMUM EFFECTIVE 150 SIZE SPRING FINGER FORCE - F/2 FINGER LENGTHS 120 **27** SENSOR ACCESSORIES* 90 20 **OHSP-017** PNP Magneto Resistive Sensor Short Barrel w/Qk Disc* 1 or 2 **OHSN-017** NPN Magneto Resistive Sensor Short Barrel w/Qk Disc* 1 or 2 60 Inductive Sensor Mounting Kit (mounts 2 sensors) SDCT25-32 30 M8 PNP Inductive Sensor with Quick Disconnect* **OISP-011** 1 or 2 M8 NPN Inductive Sensor with Quick Disconnect* OISN-011 1 or 2 0 Quick Disconnect 2 Meter Cable Length CABL-010 1 or 2 2.25 2.75 3.25 3.75 4.25 4.75 5.25 5.75 in. Quick Disconnect 5 Meter Cable Length CABL-013 1 or 2 EFFECTIVE FINGER LENGTH FROM ROTATION AXIS - L PNEUMATIC ACCESSORIES Adj. Flow Control M5 Elbow - 6mm OD Push-in (Metric) VIVE-008 1 or 2 Buna-N Seal Repair Kit **SLKT-163** SLKT-163V Viton® Seal Repair Kit **MOUNTING ACCESSORIES** Adjustment Stop Kit (1 Shielded Plate + 1 Stop) KP-CT32-BR 1 *Sensor and cable sold separately. - F/2 Static **Dynamic** Loading Capacity[†] Metric Imperial Metric Imperial Maximum Tensile T 288 N 57.6 N 65 lbs 13 lbs Maximum Compressive C 65 lbs. 288 N 13 lbs. 57.6 N Maximum Moment Mx 142 in.-lbs. 35 in.-lbs. 16 Nm 4 Nm Maximum Moment My 142 in.-lbs. 16 Nm 35 in.-lbs. 4 Nm Maximum Moment Mz 142 in.-lbs. 16 Nm 35 in.-lbs. †Capacities are per set of jaws and are not simultaneous







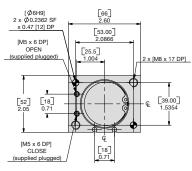


Specifications

CT-40M-RE

•		
Total Rated Grip Force, F @ 100 psi [7 bar]		
L = 2 in. [51mm] @ 0°	133 lbs.	592 N
Stroke	90° of stroke for each finger	
Weight	3.06 lbs.	1.39 Kg
Pressure Range	60-100 psi	4-7 Bar
Cylinder Bore Ø	1.575 in.	40 mm
Displacement	3.173 in ³ .	52 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation (open/close)	0.47 / 0.38 sec.	
Accuracy	±0.0036 in.	±0.09 mm
Repeatability	±0.002 in.	±0.05 mm.
Valve required to actuate single acting	single acting 3-way, 2-position	
Valve required to actuate double acting	. 4-way, 2-position	





UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Ç Dimensions are symmetrical about

0 Third Angle Projection

All Dowel Holes are SF (Slip Fit). Locational Tolerance ±.0005" or [±.013mm

0 Metric Threads Course Pitch

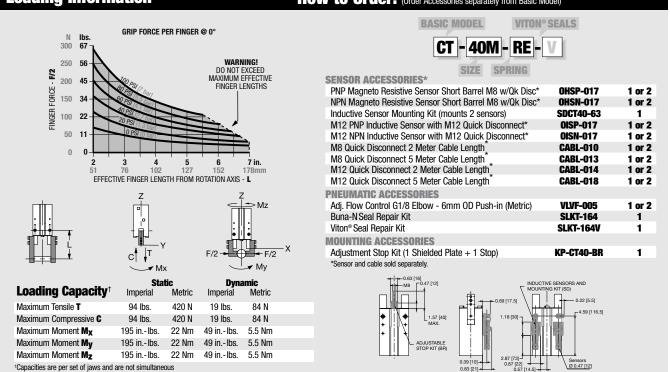
Imperial in. $0.00 = \pm .01$ $0.000 = \pm .005$ 0.0000 = +.0005

Metric [mm] $[0.] = [\pm .25]$ $[0.0] = [\pm .13]$ $[0.00] = [\pm .013]$ ເດັ ດດາ

NOTE: Jaws have to be designed for a 0° gripping position (parallel jaws). Jaws will close 1.5° past parallel. To limit shocks at the end of an opening or closing stroke, it is highly recommended to design jaws with minimal inertia (as light and short as possible). Flow Controls make it possible to reduce the rotation speed and are highly recommended.

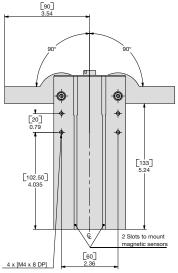
Loading Information

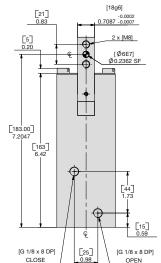
How to Order: (Order Accessories separately from Basic Model)

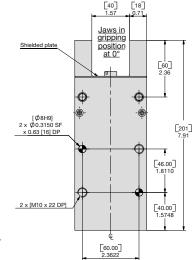


ANGULAR GRIPPER CT-50M-RE 180° SERIES







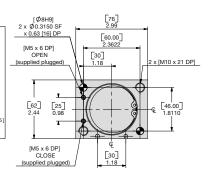


Specifications

CT-50M-RE

Total Rated Grip Force, F @ 100 psi [7 bar]		
L = 2.5 in. [64mm] @ 0°	201 lbs.	893 N
Stroke	90° of stroke for	each finger
Weight	4.87 lbs.	2.21 Kg
Pressure Range	60-100 psi	4-7 Bar
Cylinder Bore Ø	1.968 in.	50 mm
Displacement	5.614 in ³ .	92 cm ³
Temperature Range		
Standard Seals	-30°~180° F	-35°~80° C
Viton® Seals	-20°~300° F	-30°~150° C
Actuation (open/close)	0.54 / 0.42 sec.	
Accuracy	±0.0036 in.	±0.09 mm
Repeatability	±0.002 in.	±0.05 mm.
Valve required to actuate single acting		
Valve required to actuate double acting	. 4-way, 2-position	





UNLESS OTHERWISE NOTED ALL TOLERANCES ARE AS SHOWN BELOW

Dimensions are symmetrical about centerline

Third Angle Projection

†Capacities are per set of jaws and are not simultaneous

All Dowel Holes are SF (Slip Fit).
Locational Tolerance
±.0005" or [±.013mm]

Metric Threads Course Pitch

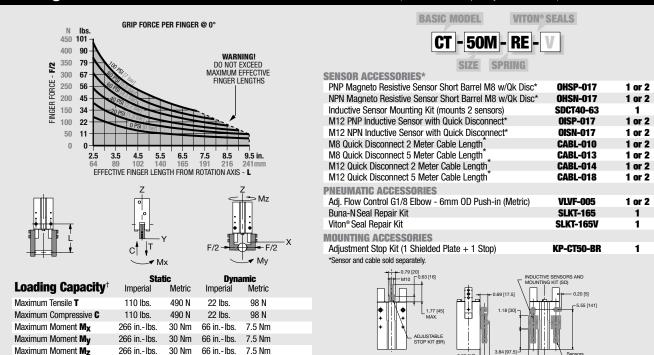
 $\begin{array}{lll} \mbox{Imperial in.} & \mbox{Metric [mm]} \\ 0.00 = \pm .01 & [0.] = [\pm .25] \\ 0.000 = \pm .005 & [0.0] = [\pm .13] \\ 0.0000 = \pm .0005 & [0.00] = [\pm .013] \end{array}$

NOTE: Jaws have to be designed for a 0° gripping position (parallel jaws). Jaws will close 1.5° past parallel. To limit shocks at the end of an opening or closing stroke, it is highly recommended to design jaws with minimal inertia (as light and short as possible).

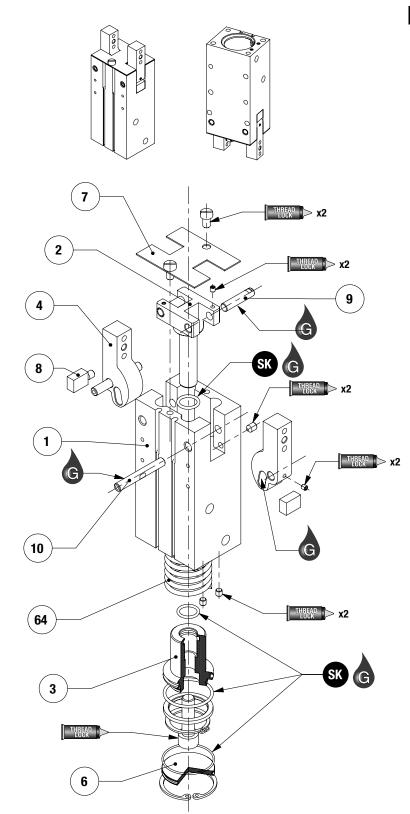
Flow Controls make it possible to reduce the rotation speed and are highly recommended.

Loading Information

How to Order: (Order Accessories separately from Basic Model)







Item	Qty	Name
01	1	Body
02	1	Driver
03	1	Piston
04	2	Jaw
05	1	Washer
06	1	Cap
07	1	Shielded Plate
80	2	Wiper Cover
09	2	Drive Pin
10	2	Pivot Pin
54	1	Magnet
64	1	Spring

DCT-RE/CT-RE Series Exploded View

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Assembly Procedure

- 1) Lubricate and install the seals into cap (x1), piston (x2) and body (x1)
- 2) If top air ports are used, clear them and plug the side air ports on the body (#1)
- 3) Lubricate the sloping rack of jaws (#4)
- 4) Install both drive pins (#9) into driver (#2) through sloping racks of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 5) Lock drive pins in the driver with screws, tightening down on to the flat surface of the pins.
- 6) Position driver and jaws assembly into body.
- 7) Install both pivot pins (#10) into body, through the bore of jaws. Check that the pin flat surface is correctly aligned before continuing with their installation.
- 8) Pivot pin locking:
 - DCT-12 (not shown): lock pivot pins into body with screws, tightening down on to the flat surface of the pins (pins are fixed into body and rotating into jaws)
- DCT-16 to CT-50: lock pivot pins into jaws with screws, tightening down on to the flat surface of the pins (pins are fixed into jaws and rotating into body)
- 9) Magnet mounting:
 - DCT-12 to DCT-20: install the magnet (#54) on the washer (#5)
 - DCT-25 to CT-50 (not shown): install magnet (#54) onto piston (#3) and lock it by means of its retaining ring.
- 10) Piston mounting:
 - DCT-12 to DCT-20: insert the spring, then the piston and the washer with magnet into body. Fix the assembly at the end of the driver with screw.
 - DCT-25 to CT-50 (not shown): insert the spring, then the piston with magnet into body. Fix the assembly at the end of the drivers with screw.
- 11) Check unit operation unladen.
- 12) Install the cap (#6) into body and lock it by means of its retaining ring.
- 13) Place both wiper covers (#8) into body and lock them with their screws.
- 14) Fix the shielded plate (#7) onto body with both screws.









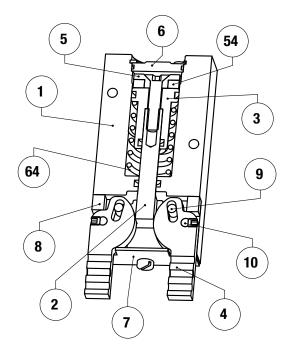








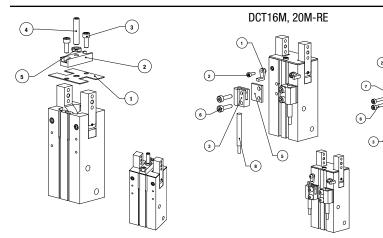


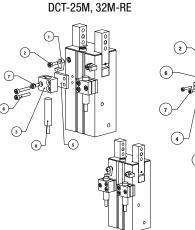


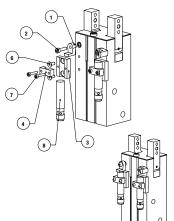
01 1 Body 02 1 Driver 03 1 Piston 04 2 Jaw 05 1 Washer 06 1 Cap 07 1 Shielded Plate 08 2 Wiper Cover 09 2 Drive Pin 10 2 Pivot Pin 54 1 Magnet	Item	Qty	Name
03 1 Piston 04 2 Jaw 05 1 Washer 06 1 Cap 07 1 Shielded Plate 08 2 Wiper Cover 09 2 Drive Pin 10 2 Pivot Pin	01	1	Body
04 2 Jaw 05 1 Washer 06 1 Cap 07 1 Shielded Plate 08 2 Wiper Cover 09 2 Drive Pin 10 2 Pivot Pin	02	1	Driver
05 1 Washer 06 1 Cap 07 1 Shielded Plate 08 2 Wiper Cover 09 2 Drive Pin 10 2 Pivot Pin	03	1	Piston
06 1 Cap 07 1 Shielded Plate 08 2 Wiper Cover 09 2 Drive Pin 10 2 Pivot Pin	04	2	Jaw
07 1 Shielded Plate 08 2 Wiper Cover 09 2 Drive Pin 10 2 Pivot Pin	05	1	Washer
08 2 Wiper Cover 09 2 Drive Pin 10 2 Pivot Pin	06	1	Cap
09 2 Drive Pin 10 2 Pivot Pin	07	1	Shielded Plate
10 2 Pivot Pin	80	2	Wiper Cover
	09	2	Drive Pin
54 1 Magnet	10	2	Pivot Pin
	54	1	Magnet
64 1 Spring	64	1	Spring

NOTE: Contact the Robohand Sales Department for a complete spare parts list with order numbers and prices.

Accessory Installation & Adjustment Instructions







CT-40M, 50M-RE

Installation - Adjustment Stop

- 1) Unscrew both screws for mounting of the shielded plate and remove it.
- 2) Fix the new shielded plate (#1) and the stop (#2) onto body with both screws (#3)
- 3) Install the locknut system (#4) and (#5) on the stop.
- 4) Tighten screw for maximum target jaw opening and lock with locknut.

Installation - Inductive Sensor Holders

- 1) Fix the flags (#1) at the end of pivot pins with their screws (#2)
- 2) Holder mounting:
- DCT-16M to DCT-32M: fix holder (#3) and spacer (#5) onto body with both screws (#6)
- CT-40M to CT-50M: fix holder (#3) onto body with both screws (#6)
- 3) Sensor mounting:
 - DCT-16M to DCT-20M: unscrew lightly both screws for mounting (#6) of holder and insert sensor (#8, not included) into it. Position sensor so that it senses up on flag. Lock the sensor by tightening both screws.
 - DCT-25M to DCT-32M: unscrew lightly screw (#7) on holder and insert sensor (#8, not included) into it. Position sensor so that it senses up the flag. Lock the sensor by tightening screw.
 - CT-40M to CT-50M: insert sensor (#8, not included) in stop into holder. Lock the sensor by tightening the collar holder with both screws (not shown).
- 4) Adjust flag position by unscrewing their screws for desired sensing positions.















